



- Notes :
1. All questions carry marks as indicated.
 2. Solve Question 1 OR Questions No. 2.
 3. Solve Question 3 OR Questions No. 4.
 4. Solve Question 5 OR Questions No. 6.
 5. Solve Question 7 OR Questions No. 8.
 6. Assume suitable data whenever necessary.
 7. Use of non programmable calculator is permitted.

1. a) To prove $Y_{BUS} = A^T \cdot [Y] \cdot A$ by singular transformation. 8
- b) For fig. 1 b shown, determine matrices A, \hat{B}, \hat{C} & K . Select node 1 as reference and elements 2 & 5 as links prove $A \cdot K^T = B$ for given network. 12

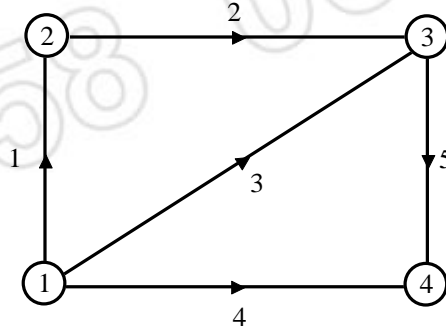


Fig. 1 b

OR

2. For the system shown in fig. 2. Obtain Y_{BUS} & Y_{Loop} by singular transformation. Also obtain Y_{Br} from Y_{BUS} . Positive sequence reactance of different elements are shown in fig. 2 in brackets. 20

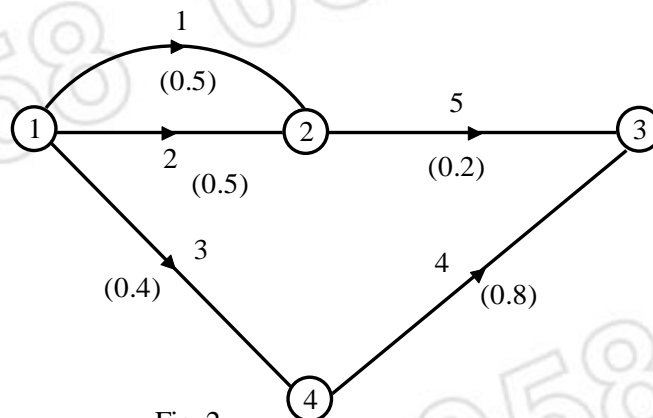


Fig. 2

3. a) The power system represented by single line diagram is shown below obtain.
- Y_{Bus} by direct inspection
 - Y_{Bus} by algorithm

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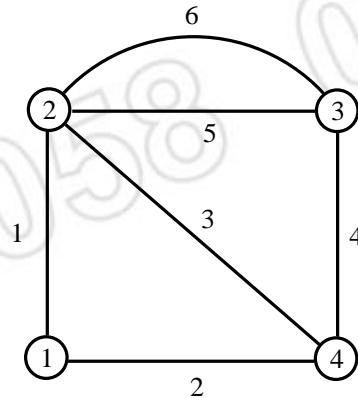


Fig. 3(a)

Positive sequence reactances of the elements are given in table.

Element No.	1	2	3	4	5	6
Reactance	0.4	0.3	0.3	0.4	0.5	0.2

- b) Derive the equations for the addition of branch to partial network.

10

OR

4. a) Form Bus impedance matrix using algorithm or the power system shown in fig. 4 a. Select Bus 1 as Ref.

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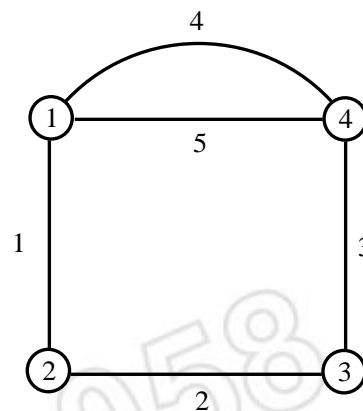


Fig. 4(a)

Reactance of the elements are shown in table.

Element No.	1	2	3	4	5
Reactance	0.13	0.1	0.12	0.15	0.14

- b) Modify Z_{Bus} if the element connected between Bus 2 & Bus 3 is removed. (Refer Fig. 4 a)
- c) Modify Z_{Bus} if the impedance of the element connected between Bus 2 & Bus 3 is required reduce to 50% of the original value. (Refer Fig. 4 a).

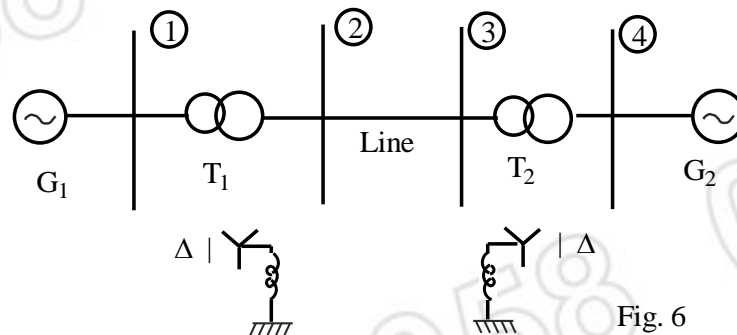
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5. a) How three phase network component is represented in impedance and admittance form? **10**
Write down performance equation in both forms.
- b) Show that the impedance matrix for three phase balanced rotating element can be diagonalised using transformation matrix ' T_S '. **10**

OR

6. For the power system shown in fig. 6. If L - G fault takes place at Bus. 3. Determine : **16**
- a) Total fault current **4**
- b) Bus voltages during fault
- Assume pre-fault bus voltages of 1 pu.



sequence reactance data is given below :

G_1 & G_2 : $X_0 = 0.08$; $X_1 = X_2 = 0.2$; $X_g = 0.03$

T_1 & T_2 : $X_0 = X_1 = X_2 = 0.1$; $X_g = 0.03$

Line : $X_0 = 0.7$ & $X_1 = X_2 = 0.4$

7. a) Give significance of load flow studies. Give classification of buses for load flow studies. **6**
- b) Draw the flow chart of Gauss - Seidal iterative method without P - V Bus. **9**
- c) Compare G. S method & Newton Raphson method for load flow solution. **5**

OR

8. 50 Hz synchronous machine is transferring power to infinite bus over a transmission network. The transfer reactances in pu between machine and infinite bus are **20**
- Prefault : 0.65
- During fault : 4.0
- Post Fault : 2.0
- Prefault power transfer is 1.0 pu
- Voltage of infinite bus is 1.0 pu
- Voltage behind transient reactance is 1.5 pu
- Inertia Constant $H = 3.5$ pu
- Determine variation of rotor angle and velocity versus t using modified Eulers method.
- Take time step of 0.05 sec
- Fault is cleared at 0.1 sec. Carry out calculations upto 3 iterations.
